

Calculation of the covariance function of a vector autoregression

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1 From the Yule-Walker equations

Let Γ_k be the covariance at lag k of a VAR(p) model for an m -dimensional process x_t , with given coefficients Φ_k and innovation variance V :

$$x_t = \Phi_1 x_{t-1} + \Phi_2 x_{t-2} + \cdots + \Phi_p x_{t-p} + e_t, \quad (1)$$

The Yule-Walker equations given in the book as (2.5) and (2.6) can be combined into a $(p+1) \times (p+1)$ block matrix equation:

$$\begin{pmatrix} 1 & -\Phi_1 & -\Phi_2 & \cdots & -\Phi_p \end{pmatrix} \begin{pmatrix} \Gamma_0 & \Gamma_1 & \cdots & \cdots & \Gamma_{(p)} \\ \Gamma_{-1} & \Gamma_0 & \cdots & \cdots & \Gamma_{(p-1)} \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \Gamma_{-p} & \Gamma_{-(p-1)} & \cdots & \cdots & \Gamma_0 \end{pmatrix} = \begin{pmatrix} V & 0 & \cdots & \cdots & 0 \end{pmatrix} \quad (2)$$

Now let $\Phi_0 = I$ and write Φ for $-Phi$, reversing the sign convention in (1). Then (2) can be re-arranged as linear equations for the elements of $\Gamma_0 \dots \Gamma_p$. However, they cannot be solved by block matrix algebra such as that used in the Whittle recursive method to derive the coefficients Φ_k from the covariances Γ_k . In terms of the elements of the quantities involved (and recalling $\Gamma_{-k} = \Gamma'_k$) we can write the set of equations:

$$\sum_{k_2=0}^{p-k_1} \sum_{j_2=1}^m \Phi_{i_1 j_2 k_1+k_2} \Gamma_{j_1 j_2 k_2} + \sum_{k_2=1}^{k_1} \sum_{j_2=1}^m \Phi_{i_1 j_2 k_1-k_2} \Gamma_{j_2 j_1 k_2} = V_{i_1 j_1} \delta_{k_1,0} \quad (3)$$

for $i_1 = 1 \dots m, j_1 = 1 \dots m, k_1 = 0 \dots p$,

where $\delta_{i,j} = 1$ if $i = j$, else is zero. The coefficient of $\Gamma_{i_2 j_2 k_2}$ in the equations is then

$$\Phi_{i_1 j_2 k_1+k_2} \delta_{j_1, i_2} + \Phi_{i_1 i_2 k_1-k_2} \delta_{j_1, j_2}.$$

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These are the equations solved by the MATLAB function `VARcovfunX.m` using indices for the rows and columns which are incremented as the variables i_1, j_1, k_1 and i_2, j_2, k_2 loop through their ranges. Because Γ_0 is symmetric, the rows and columns of its sub-diagonal elements are removed from the equations and its semi-diagonals used as unknowns.

After solving for $\Gamma_0 \dots \Gamma_p$ the higher lag covariances are calculated using (2.25) in the book.

2 From the covariance generating function

Section 2.10 of the book presents the covariance generating function of a VAR(p) model which may be expressed in terms of its positive and negative powers of z as

$$\Gamma(z) = \Phi(z)^{-1} V \{ \Phi(z^{-1})' \}^{-1} = \Phi(z)^{-1} A(z) + A(z^{-1})' \{ \Phi(z^{-1})' \}^{-1}, \quad (4)$$

where

$$A(z) = A_0 + A_1 z + \dots + A_p z^p, \quad (5)$$

with A_0 constrained to be upper triangular for uniqueness. Then on expanding we obtain

$$\Phi(z)^{-1} A(z) = A_0 + \Gamma_1 z + \Gamma_2 z^2 + \dots \quad (6)$$

with $\text{Var } x_t = \Gamma_0 = A_0 + A_0'$.

The equations to be solved for $A(z)$ come from multiplying out (4) as

$$V = A(z) \Phi(z^{-1})' + \Phi(z) A(z^{-1})'. \quad (7)$$

Equating coefficients of powers of z gives linear equations for the coefficients of $A(z)$ as

$$\sum_{k_2=k_1}^p \sum_{j_2=1}^m A_{i_1 j_2 k_2} \Phi_{j_1 j_2 k_2 - k_1} + \sum_{k_2=0}^{p-k_1} \sum_{j_2=1}^m \Phi_{i_1 j_2 k_1 + k_2} A_{j_1 j_2 k_2} = V_{i_1 j_1} \delta_{k_1, 0} \quad (8)$$

for $i_1 = 1 \dots m, j_1 = 1 \dots m, k_1 = 0 \dots p$.

The coefficient of $A_{i_2 j_2 k_2}$ in the equations is then

$$\Phi_{j_1 j_2 k_2 - k_1} \delta_{i_1, i_2} + \Phi_{i_1 j_2 k_2 + k_1} \delta_{j_1, i_2}.$$

We are here using the same sign convention for Φ_k as in (3). These are the equations solved by the MATLAB function `VARcovfun.m` using indices for the rows and columns which are incremented as the variables i_1, j_1, k_1 and i_2, j_2, k_2 loop through their ranges. They are similar, but not identical, to the equations (3). After obtaining $A(z)$ the covariances are generated by expanding (6) using the recurrence

$$H_k = A_k + \sum_{i=1}^p \Phi_i H_{k-i}; \quad k = 1, 2, \dots \quad (9)$$

taking $H_0 = A_0$ and $H_k = 0$ for $k < 0$, and with the original sign convention for Φ_k restored. Then $\Gamma_0 = H_0 + H_0'$ and $\Gamma_k = H_k$ for $k > 0$.